# A new approach to electromagnetism in anisotropic spaces

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#### Abstract

Anisotropy of a space naturally leads to direction dependent electromagnetic tensors and electromagnetic potentials. Starting from this idea and using variational approaches and exterior derivative formalism, we extend some of the classical equations of electromagnetism to anisotropic (Finslerian) spaces. The results differ from the ones obtained by means of the known approach in [3], [4].

**Keywords:** anisotropy, Finsler space, electromagnetic tensor

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#### 1 Introduction

In anisotropic spaces, where the fundamental metric tensor depends on the directional variables, the electromagnetic-type tensor F and accordingly, the electromagnetic potential A, may also depend on these.

Starting from this idea, we propose a generalization of the electromagnetic tensor, of the notion of current and of the corresponding Maxwell equations - based on variational methods and exterior derivative formalism. We chose those anisotropic spaces which provide the simplest equations, namely, Finslerian ones. A similar approach for a particular class of Finsler spaces was already considered by the authors in [1].

When dealing with the equations of electromagnetism, one can either: 1) consider as a fundamental object the electromagnetic tensor F satisfying the homogeneous Maxwell equations (written in a condensed manner as dF = 0) and deduce by Poincaré lemma the existence of a potential 1-form A such that F = dA, or, conversely: 2) consider the potential 1-form A as a fundamental object, and define the electromagnetic tensor as its exterior derivative - thus getting the homogeneous Maxwell equations as identities.

In order to realize how the electromagnetic tensor and Lorentz force might look like in anisotropic spaces, it appeared as more convenient to use for the beginning the second approach, and then point out (Theorem 9) that using the first one, we are led to similar results.

The theory we are going to develop stems from considering a direction dependent potential 4-covector field A = A(x, y), (where,  $x = (x^i)$  are the space-time coordinates and  $y = (y^i)$ , the directional ones) as arising from a Lagrangian. Namely, it appears as reasonable to consider the following Lagrangian  $\mathcal{L}$ , providing the Lorentz force in Finsler spaces:

$$\mathcal{L} = \frac{1}{2}g_{ij}(x,y)y^{i}y^{j} + \frac{q}{c}L_{1}(x,y), \ y^{i} = \dot{x}^{i},$$

where  $L_1$  is a 1-homogeneous function in y,  $(L_1(x, \lambda y) = \lambda L_1(x, y), \lambda \in \mathbb{R})$  and g is the Finslerian metric tensor. Then, the Liouville (canonical) 1-form

$$\theta = \frac{\partial \mathcal{L}}{\partial y^i} dx^i$$

and the Poincaré 2-form  $\omega = d\theta$  (where d denotes exterior derivative) attached to  $\mathcal{L}$  carry information on both the metric of the space and on electromagnetic properties. The potential 1-form A can be defined as  $A = \theta - y_i dx^i$ , which is,

$$A = A_i(x, y)dx^i, \quad A_i = \frac{\partial L_1}{\partial y^i}.$$

and the electromagnetic tensor, as  $F = \omega - g_{ij} \delta y^j \wedge dx^i$ , which is nothing but the exterior derivative of A:

$$F = dA = \frac{1}{2} (A_{j|i} - A_{i|j}) dx^i \wedge dx^j - \frac{\partial A_i}{\partial y^a} dx^i \wedge \delta y^a,$$

(where bars denote Chern type covariant derivatives)

The equations of motion of charged particles are then

$$\frac{\delta y^i}{dt} = \frac{q}{c} F^i_{\ j} y^j + \frac{q}{c} \tilde{F}^i_{\ a} \frac{\delta y^a}{dt}, \quad y^i = \dot{x}^i$$

where  $\frac{\delta y^i}{dt} = \frac{dy^i}{dt} + \Gamma^i{}_{jk}(x,y)y^jy^k$ , and  $F_{ih} = A_{j|i} - A_{i|j}$ ,  $\tilde{F}_{ia} = -\frac{\partial A_i}{\partial y^a}$  are the components of the electromagnetic tensor above defined.

Maxwell equations in Finsler spaces are obtained as

$$dF = 0 (1)$$

$$(d * F) = \frac{\beta}{4\alpha} (*\mathcal{J}). \tag{2}$$

where \* denotes Hodge star operator, and the *current*  $\mathcal{J}$  is a vector field on TM, and  $\alpha, \beta$  are constants. In order to obtain the expression for currents, we

also perform a variational approach (with an integrand defined on a domain in TM).

From a physical point of view, we notice the appearance of an additional term (reminding inertial forces) in the expression of Lorentz force (15), as well as the appearance of a correction to the usual expression of currents, (24).

The generalized current  $\mathcal{J} = J^i \delta_i + \tilde{J}^a \dot{\partial}_a$  obeys the continuity equation  $div\mathcal{J} = 0$ . The horizontal component  $J^i$  is equal to the regular current plus a correction due to anisotropy, while the vertical one  $\tilde{J}^a$  plays the role of compensating quantity so as to have the continuity equation satisfied.

## 2 Pseudo-Finsler spaces

Let M be a 4-dimensional differentiable manifold of class  $\mathcal{C}^{\infty}$ , thought of as spacetime manifold,  $(TM, \pi, M)$  its tangent bundle and  $(x^i, y^i)_{i=\overline{1,4}}$  the coordinates in a local chart on TM. By "smooth" we shall always mean  $\mathcal{C}^{\infty}$ -differentiable. Also, we denote partial derivation with respect to  $x^i$  by  $_{,i}$  and partial derivation with respect to  $y^i$ , by a dot:  $_{i}$ .

A pseudo-Finslerian function on M, is a function  $\mathcal{F}:TM\to\mathbb{R}$  with the properties, [7]:

- 1.  $\mathcal{F} = \mathcal{F}(x, y)$  is smooth for  $y \neq 0$ ;
- 2.  $\mathcal{F}$  is positive homogeneous of degree 1, i.e.,  $\mathcal{F}(x, \lambda y) = \lambda \mathcal{F}(x, y)$  for all  $\lambda > 0$ ;
- 3. The pseudo-Finslerian metric tensor:

$$g_{ij}(x,y) = \frac{1}{2} \frac{\partial^2 \mathcal{F}^2}{\partial y^i \partial y^j}$$
 (3)

is nondegenerate:  $\det(g_{ij}(x,y)) \neq 0, \ \forall x \in M, \ y \in T_x M \setminus \{0\}.$ 

Particularly, we shall consider that the metric has signature (+, -, -, -).

The equations of geodesics  $s \mapsto (x^i(s))$  of a Finsler space  $(M, \mathcal{F})$  are

$$\frac{dy^{i}}{ds} + 2G^{i}(x, y) = 0, \quad y^{i} = \dot{x}^{i}.$$

These equations give rise to the  $Cartan\ nonlinear\ connection$  on TM, of local coefficients

$$N^{i}_{\ j} = \frac{\partial G^{i}}{\partial y^{j}}.$$

Let

$$\delta_i = \frac{\partial}{\partial x^i} - N^a_{\ i} \frac{\partial}{\partial y^a}, \quad \dot{\partial}_a = \frac{\partial}{\partial y^a}$$

be the adapted basis corresponding to the Cartan nonlinear connection and

$$(dx^i, \ \delta y^a = dy^a + N^a_{\ i} dx^i),$$

its dual basis. We will also denote by semicolons adapted derivatives:

$$f_{:i} = \delta_i f, \quad \forall f \in \mathcal{F}(TM).$$

Any vector field V on TM can be written as  $V=V^i\delta_i+\tilde{V}^a\dot{\partial}_a$ ; the component  $hV=V^i\delta_i$  is a vector field, called the *horizontal* component of V, while  $vV=\tilde{V}^a\dot{\partial}_a$  is its vertical component. Similarly, a 1-form  $\omega$  on TM can be decomposed as  $\omega=\omega_i dx^i+\tilde{\omega}_a\delta y^a$ , with  $h\omega=\omega_i dx^i$  called the *horizontal* component, and  $v\omega=\tilde{\omega}_a\delta y^a$  the vertical one.

In terms of the Cartan nonlinear connection, the divergence of a vector field  $V = V^i \delta_i + \tilde{V}^a \dot{\partial}_a \in \mathcal{X}(TM)$ , is obtained, [9] (from  $d(*V^{\flat}) = divV \sqrt{G} dx^1 \wedge ... \wedge \delta y^4$ ) as

$$divV = \frac{1}{\sqrt{G}} \delta_i(\tilde{V}^i \sqrt{G}) - N^a_{i \cdot a} V^i + \frac{1}{\sqrt{G}} (\tilde{V}^a \sqrt{G})_{\cdot a}.$$

where  $G = \det(G_{\alpha\beta})$  is the determinant of the Sasaki lift of  $g_{ij}$ :

$$G_{\alpha\beta}(x,y) = g_{ij}(x,y)dx^{i} \otimes dx^{j} + g_{ij}(x,y)\delta y^{i} \otimes \delta y^{j}. \tag{4}$$

Also, it is convenient to express the electromagnetic tensor in terms of the Chern linear connection  $C\Gamma(N) = (L^i{}_{ik}, 0)$  of local coefficients:

$$L^{i}_{jk} = \frac{1}{2}g^{ih}(g_{hj;k} + g_{hk;j} - g_{jk;h}).$$

We denote by |i| and i the corresponding covariant derivations

$$X^{j}_{|i} = \delta_{i}X^{j} + L^{j}_{ki}X^{i}, \quad X^{j}_{\cdot i} = \frac{\partial X^{j}}{\partial y^{i}},$$

(where  $X^{j}$  are local coordinates of a vector field X on TM). Then, we have

$$g_{ij|k} = 0$$

(the connection is h-metric). Also, the Chern connection above, there hold the equalities  ${\bf r}$ 

$$y_{i|j} = 0. (5)$$

The vertical endomorphism or almost tangent structure of TTM, [7], is the  $\mathcal{F}(TM)$ -linear function  $\mathbf{J}:TTM\to TTM$ , which acts on the elements of the adapted basis as

$$\mathbf{J}(\delta_i) = \dot{\partial}_i, \quad \mathbf{J}(\dot{\partial}_i) = 0,$$

where  $\mathcal{F}(TM)$  denotes the set of smooth real valued functions defined on TM. For a smooth function  $f: TM \to \mathbb{R}$ , the vertical differential  $d_{\mathbf{J}}f$ , [7], is defined by  $d_{\mathbf{J}}f = df \circ \mathbf{J}$ ; in local writing,

$$d_{\mathbf{J}}f = \frac{\partial f}{\partial u^j} dx^j.$$

Whenever convenient or necessary to make a clear distinction, we shall denote by i, j, k, ... indices corresponding to horizontal geometrical objects, and by a, b, c, ... indices corresponding to vertical ones.

# 3 Direction dependent electromagnetic potential. Electromagnetic tensor

In anisotropic spaces and particularly, in Finsler spaces, the components of an electromagnetic-type tensor  $F_{ij}$ ,  $F^{ij}$ ,  $F^{ij}$  and accordingly, of the electromagnetic potential 1-form A basically depend on the directional variables  $y^{i}$ , i = 1, ..., 4.

In order to make sure of this, let us notice the following simple example. In isotropic (pseudo-Riemannian) spaces with vanishing Ricci tensor, under some simplifying assumptions, the components of the free electromagnetic potential 4-vector  $A^i = A^i(x)$  obey Maxwell- de Rham equations, [8]:

$$g^{ij}(x)\nabla_i\nabla_j(A^k) = 0,$$

where  $\nabla_k = \nabla_{\frac{\partial}{\partial x^k}}$  denotes covariant derivative with respect to Levi-Civita connection.

When passing to anisotropic spaces with metric  $g_{ij} = g_{ij}(x, y)$ , the solution of such an equation would generally depend on the directional variables  $y^i$  (not to mention that the equation itself could become more complicated). So, it is meaningful to consider that the potential 4-vector (and, accordingly, the corresponding 1-form A) also depends on the directional variables  $y = (y^i)$ .

Let us define this potential.

In *isotropic* (pseudo-Riemannian) spaces, the Lagrangian providing Lorentz force is  $L(x,y) = \frac{1}{2}g_{ij}(x)y^iy^j + \frac{q}{c}A_i(x)y^i$ ,  $y^i = \dot{x}^i$ , where q is the electric charge, and  $A_i(x)$  are the covariant components of the 4-vector potential.

For Finsler spaces, let us relax the condition that  $L_1 = A_i y^i$  should be a linear function of y: namely, instead of linearity, we impose that  $L_1$  should be just 1-homogeneous in y, which is equivalent to

$$\frac{\partial L_1}{\partial u^i} y^i = L_1.$$

From a physical point of view, this means that we will allow the potential A to depend on the directional variable y, but not on the magnitude of y. That

is, in order to obtain the expression for Lorentz force in Finsler spaces, we consider the Lagrangian

$$\mathcal{L} = \frac{1}{2}g_{ij}(x,y)y^{i}y^{j} + \frac{q}{c}L_{1},$$
(6)

where  $L_1 = L_1(x, y)$  is a scalar function which is 1-homogeneous in the directional variables.

Let

$$\theta = d_{\mathbf{J}} \mathcal{L},$$

be the Liouville (canonical) 1-form attached to  $\mathcal{L}$ . In local coordinates,

$$\theta = \frac{\partial \mathcal{L}}{\partial y^i} dx^i = (y_i + \frac{q}{c} \frac{\partial L_1}{\partial y^i}) dx^i.$$

**Definition 1** We call potential 1-form A, the 1-form given by

$$\frac{q}{c}A = \theta - y_i dx^i.$$

In local writing,

$$A = A_i(x, y)dx^i, \qquad A_i(x, y) = \frac{\partial L_1}{\partial y^i}.$$
 (7)

By the 1-homogeneity of  $L_1$ , there holds  $L_1 = A_j(x,y)y^j$ , hence it makes sense

**Definition 2** We call Lorentz force Lagrangian in the Finsler space  $(M, \mathcal{F})$ , the following function

$$\mathcal{L}(x,y) = \frac{1}{2}g_{ij}(x,y)y^{i}y^{j} + \frac{q}{c}A_{i}(x,y)y^{i}.$$
 (8)

The quantities  $A_j = A_j(x, y)$ , thus, become the components of a direction dependent electromagnetic potential. They have the property

$$A_{i \cdot k} y^k = 0; \ A_{i \cdot k} y^i = 0.$$
 (9)

**Remark 3** In isotropic spaces, there exists only one potential 4-vector providing a given  $L_1 = A_i(x)y^i$  (which is  $A_i = \frac{\partial L_1}{\partial y^i}$ ). In anisotropic spaces, there exist infinitely many covector fields  $A_i = A_i(x,y)$  with  $A_iy^i = L_1$  for a fixed  $L_1$ . Among them, (7) is the one which gives the simplest equations of motion.

Taking (5) into account, the exterior derivative of the 1-form  $\theta$  yields the following gravito-electromagnetic 2-form:

$$\omega = d\theta = \frac{1}{2} (A_{j|i} - A_{i|j}) dx^i \wedge dx^j - (g_{ia} + A_{i \cdot a}) dx^i \wedge \delta y^a, \tag{10}$$

which contains information both on the metric structure of the space and on the electromagnetic field.

#### Particular cases:

1. If  $A_i = A_i(x)$  is isotropic, then  $\tilde{F}_{ia} = 0$  and the 2-form  $\omega$  is simply

$$\omega = \frac{1}{2} (A_{j|i} - A_{i|j}) dx^i \wedge dx^j - g_{ia} dx^i \wedge \delta y^a,$$

which is similar to the expression in [4].

2. If  $A_i = 0$  (no electromagnetic potential), then  $\theta$  is the Hilbert 1-form of the space,

$$\theta = u_i dx^i$$

and  $\omega$ , the fundamental 2-form of  $(M, \mathcal{F})$ , [7]:

$$\omega = g_{ia}\delta y^a \wedge dx^i.$$

**Definition 4** We call electromagnetic tensor in the Finslerian space,  $(M, \mathcal{F})$ , the following 2-form on TM:

$$F = \omega + g_{ia}dx^i \wedge \delta y^a,$$

The above definition is equivalent to

$$F = dA. (11)$$

In local coordinates, we have

$$F := \frac{1}{2} F_{ij} dx^i \wedge dx^j + \tilde{F}_{ia} dx^i \wedge \delta y^a, \tag{12}$$

where

$$F_{ij} = A_{j|i} - A_{i|j}, \quad \tilde{F}_{ia} = -A_{i \cdot a}, \quad \tilde{F}_{ai} = A_{i \cdot a}.$$
 (13)

In relation (13) we denoted indices corresponding to vertical geometric objects by different letters a, b, c..., in order to point out the antisymmetry of F.

The above is a natural generalization of the electromagnetic tensor, for anisotropic Finslerian spaces. The new component,  $\tilde{F}_{ia}$ , will play an important role in the equations of motion of charged particles (see Section 4).

**Remark:** The electromagnetic tensor F remains invariant under transformations

$$A(x,y) \mapsto A(x,y) + d\lambda(x),$$

where  $\lambda: M \to \mathbb{R}$  is a scalar function, since  $d(A+d\lambda) = dA + d(d\lambda) = dA$ .

**Particular case:** If A = A(x) does not depend on the directional variables, we get  $\tilde{F}_{ia} = 0$  and

$$F = \frac{1}{2}(A_{j|i} - A_{i|j})dx^i \wedge dx^j,$$

which is similar to the expression in [3], [4].

#### 4 Lorentz force

The equations of motion of a charged particle in an electromagnetic field can be obtained from the variational procedure applied to the Lagrangian (8). The corresponding Euler-Lagrange equations  $\frac{\partial \mathcal{L}}{\partial x^i} - \frac{d}{dt}(\frac{\partial \mathcal{L}}{\partial u^i}) = 0$  lead to

$$g_{kh}(\frac{dy^h}{dt} + 2G^i) + \frac{q}{c}(\frac{\partial A_k}{\partial x^h} - \frac{\partial A_h}{\partial x^k})y^h + \frac{q}{c}A_{k \cdot h}\frac{dy^h}{dt} = 0, \quad y^i = \dot{x}^i.$$
 (14)

Writing the second term above, in terms of covariant derivatives and taking into account (13) and the equality  $\frac{\delta y^i}{dt} = \frac{dy^i}{dt} + N^i_{\ j} y^j = \frac{dy^i}{dt} + 2G^i$ , we get

**Proposition 5** (Lorentz force law): The extremal curves  $t \mapsto (x^i(t)) : [0,1] \to \mathbb{R}^4$  of the Lagrangian (8) are given by

$$\frac{\delta y^i}{dt} = \frac{q}{c} F^i_{\ h} y^h + \frac{q}{c} \tilde{F}^i_{\ a} \frac{\delta y^a}{dt},\tag{15}$$

An elegant equivalent writing of the above can be obtained in terms of the gravito-electromagnetic 2-form  $\omega$  in (10). In order to obtain this, let us write

$$\omega = \frac{1}{2}\omega_{ij}dx^i \wedge dx^j + \tilde{\omega}_{ia}dx^i \wedge \delta y^a,$$

where  $\omega_{ij} = \frac{q}{c} F_{ij}$ ,  $\tilde{\omega}_{ia} = (\frac{q}{c} \tilde{F}_{ia} - g_{ia})$ . We are led to

**Proposition 6** The equations of motion of a charged particle in electromagnetic field in Finslerian spaces are

$$\omega_{ij}(x,y)\frac{dx^j}{dt} + \tilde{\omega}_{ia}(x,y)\frac{\delta y^a}{dt} = 0, \quad y = \dot{x}.$$
 (16)

Remark 7 1. In the case of an anisotropic potential A, there appears an additional term

$$\tilde{F}^{i}(x,y) := \tilde{F}^{i}_{a} \frac{\delta y^{a}}{dt} = -g^{ik}(x,y)\tilde{F}_{ka}(x,y)\frac{\delta y^{a}}{dt}$$
(17)

in the equations of motion, in comparison to the isotropic case.

2. Both the "traditional" Lorentz force (given by  $F^i = F^i_h y^h$ ) and the correction  $\tilde{F}$  are orthogonal to the velocity 4-vector  $y = \dot{x}$ :

$$g_{ij}F^{i}y^{j} = 0, g_{ij}\tilde{F}^{i}y^{j} = 0.$$
 (18)

3. The above defined  $F_{kh}$ ,  $\tilde{F}_{ka}$ ,  $F^{\iota}$ ,  $\tilde{F}^{i}$  are components of distinguished tensor fields, [3].

**Physical interpretation:** The usual interpretation of the extremal curves are the equations of motion. Therefore, the expression in the right hand side of (15) presents the Lorentz force in anisotropic spaces. We see that its first term which is common with the isotropic case is proportional to velocity, while the second term is proportional to acceleration which brings to mind the idea of an "inertial force" in accelerated reference frames.

## 5 Homogeneous Maxwell equations

Taking into account that F = dA, we immediately get the identity dF = d(dA) = 0. In other words:

**Proposition 8** There holds the generalized homogeneous Maxwell equation:

$$dF = 0, (19)$$

where F is the electromagnetic tensor (12), (13), and d denotes exterior derivative.

In local coordinates, the homogeneous Maxwell equation is read as:

$$F_{ij|k} + F_{ki|j} + F_{jk|i} = -\sum_{(i,j,k)} R^b_{jk} \tilde{F}_{ib};$$
  
$$\tilde{F}_{aj|k} + \tilde{F}_{ka|j} + F_{jk\cdot a} = 0$$
  
$$\tilde{F}_{ka\cdot b} + \tilde{F}_{bk\cdot a} = 0.$$

The first set in the above is the analogue (in adapted coordinates) of the regular homogeneous (sourceless) Maxwell equations.

There also hold the relations

$$\tilde{F}_{ia}y^i = 0, \ \tilde{F}_{ia}y^a = 0,$$
 (20)

entailed by the 1-homogeneity of  $L_1$  and the fact that  $A_i = \frac{\partial L_1}{\partial y^i}$  are its y-partial derivatives.

Conversely, on a topologically "nice enough" domain, we have

**Theorem 9** If on a contractible subset of  $T\mathbb{R}^4$  we define the electromagnetic tensor as a 2-form

$$F := \frac{1}{2} F_{ij} dx^i \wedge dx^j + \tilde{F}_{ia} dx^i \wedge \delta y^a,$$

on the respective subset, satisfying

$$dF = 0;$$

then there exists a horizontal 1-form

$$A = A_i(x, y)dx^i$$

such that F = dA. Moreover, if  $\tilde{F}_{ia}y^i = 0$  and  $\tilde{F}_{ia}y^a = 0$ , then  $A_i = \frac{\partial L_1}{\partial y^i}$  for some 1-homogeneous in y scalar function  $L_1(x, y)$ .

**Proof:** By Poincaré lemma, we deduce that there exists a 1-form

$$\bar{A} = \phi_i(x, y)dx^i + \psi_a(x, y)\delta y^a$$

such that  $F = d\bar{A}$ . By computing  $d\bar{A}$  and equating its components with those of F, we get

$$F_{ij} = \phi_{j|i} - \phi_{i|j} - R^a_{ij}\psi_a; \quad \tilde{F}_{ia} = -\phi_{i\cdot a} - \psi_{a\cdot i}, \quad 0 = \psi_{a\cdot b} - \psi_{b\cdot a}.$$

From the last relation, we get that there exists a scalar function  $\psi = \psi(x,y)$  such that  $\psi_a = \psi_{\cdot a}$ ,  $a = \overline{1,4}$ . Then, by direct computation, it follows that, if we build the following *horizontal* 1-form:

$$A := A_i dx^i, \quad A_i := \phi_i + \delta_i \psi,$$

then our 2-form F is none but its exterior differential: F = dA.

Further, from  $\tilde{F}_{ia}y^i = 0$ , we get  $A_{i\cdot a}y^i = 0$ , which is,  $(A_iy^i)_{\cdot a} = A_{\cdot a}$ . By setting  $L_1 = A_iy^i$  and re-denoting indices, we have  $A_i = \frac{\partial L_1}{\partial y^i}$ . 1-homogeneity of  $L_1$  now follows from  $\tilde{F}_{ia}y^a = 0$ , q.e.d.

# 6 Currents in Finslerian spaces

In the classical Riemannian case, the inhomogeneous Maxwell equation  $d(*F) = 4\pi * J$  can be obtained by means of the variational principle applied to  $\int (\alpha F_{ij} F^{ij} - \beta J^k A_k) \sqrt{-g} d\Omega$ , [6], where J denotes the 4-vector of a current,  $\alpha$  and  $\beta$  are constants,  $g = \det(g_{ij})$  and  $d\Omega = dx^1 \wedge dx^2 \wedge dx^3 \wedge dx^4$ , and the integral is taken on some domain in  $M = \mathbb{R}^4$ .

In our case, the quantities  $F_{ij}$ ,  $F^{ij}$ ,  $A_k$  depend on y, hence the integrand is actually defined on some domain in TM. It is natural to look for a generalization of the above Lagrangian to TM. Also, it is reasonable to think of the current as of a vector field on TM:

$$\mathcal{J} = J^{i}(x, y)\delta_{i} + \tilde{J}^{a}(x, y)\dot{\partial}_{a}. \tag{21}$$

The meaning of the quantities  $\tilde{J}^a$  will reveal itself later.

Let us consider  $A_i = A_i(x, y)$  and the following integral of action on some domain in TM:

$$I = \int (\alpha (F_{ij}F^{ij} + \tilde{F}_{ia}\tilde{F}^{ia} + \tilde{F}_{ai}\tilde{F}^{ai} - \beta J^k A_k)\sqrt{G}d\Omega,$$
 (22)

where  $d\Omega = dx^1 \wedge ...dx^4 \wedge \delta y^1 \wedge ...\delta y^4$ ,  $G = \det(G_{\alpha\beta})$ , and  $G_{\alpha\beta}$  denotes the Sasaki lift of g.

In order to make physical sense for the above, we need to adjust measurement units so as to have  $[F_{ij}] = [\tilde{F}_{ia}]$ . Hence, let

$$u^a = \frac{1}{H}y^a,$$

be the fibre coordinates on TM, where, H is a constant (ex:  $[H] = \frac{1}{\sec}$ ) meant to have the same measurement units for  $x^i$  and  $u^a$ :  $[x^i] = [u^a]$ , (consequently, also  $[F_{ij}(x,u)] = [\tilde{F}_{ia}(x,u)]$ ). Also, let  $\dot{\partial}_a = \frac{\partial}{\partial u^a}$ . The integral (22) only involves the horizontal part  $h\mathcal{J} = J^i(x,u)\delta_i$  of the extended current  $\mathcal{J}$ , let us denote it by

$$J = J^i(x, u)\delta_i$$
.

The integral of action (22) is  $I = \int (\alpha(F_{ij}F^{ij} + 2\tilde{F}_{ia}\tilde{F}^{ia}) - \beta J^k A_k)\sqrt{G}d\Omega$ . By varying the potentials  $A_k$ , we get

$$\boldsymbol{\delta}_{A}I = \int \{4\alpha(\delta A_{i;j}F^{ji} - \delta A_{i\cdot a}\tilde{F}^{ia}) - \beta J^{k}\boldsymbol{\delta}A_{k})\}\sqrt{G}d\Omega,$$

which is

$$\delta_A I = \int 4\alpha \{ (\delta A_i F^{ji} \sqrt{G})_{;j} - (\delta A_i \tilde{F}^{ia} \sqrt{G})_{\cdot a} - (F^{ji} \sqrt{G})_{;j} \delta A_i + (\tilde{F}^{ia} \sqrt{G})_{\cdot a} \delta A_i \} - \beta J^i \delta A_i \sqrt{G} d\Omega.$$

We have  $(\delta A_i F^{ji} \sqrt{G})_{;j} = div(\delta A_i F^{ji} \sqrt{G}) + \delta A_i F^{ji} \sqrt{G} N^a_{j\cdot a}, \quad (\delta A_i \tilde{F}^{ia} \sqrt{G})_{\cdot a} = div(\delta A_i \tilde{F}^{ia} \sqrt{G}).$  The divergences can be transformed into integrals on the boundary if the domain of integration; by considering variations  $\delta A_i$  which vanish on this boundary, it remains

$$\delta_A I = \int \left\{ 4\alpha \left( (F^{ij} \sqrt{G})_{;j} - F^{ij} \sqrt{G} N^a_{j \cdot a} + (\tilde{F}^{ia} \sqrt{G})_{\cdot a} \right) - \beta J^i \sqrt{G} \right\} \delta A_i d\Omega = 0.$$

**Proposition 10** There holds the generalized inhomogeneous Maxwell equation:

$$\frac{1}{\sqrt{G}}\{(F^{ij}\sqrt{G})_{;j} - F^{ij}N^a_{j\cdot a}\sqrt{G}\} + \frac{1}{\sqrt{G}}(\tilde{F}^{ia}\sqrt{G})_{\cdot a} = \frac{\beta}{4\alpha}J^i, \tag{23}$$

**Particular case:** If the space is pseudo-Riemannian, then  $A_i = A_i(x)$  and, [2], [3],  $N^a_{\ j} = \gamma^a_{\ jk}(x)y^k$  (where  $\gamma^a_{\ jk}$  denote the Christoffel symbols of the metric g), hence  $N^a_{\ j\cdot a} = \gamma^a_{\ ja}$ . We get

$$\begin{split} &\frac{1}{\sqrt{G}}\{(F^{ij}\sqrt{G})_{;j}-F^{ij}N^{a}_{j\cdot a}\sqrt{G}\} = \frac{1}{\sqrt{G}}\{(F^{ij}\sqrt{G})_{,\ j}-(N^{a}_{\ j}F^{ij}\sqrt{G})_{\cdot a}\} = \\ &\frac{1}{\sqrt{G}}\{F^{ij}_{\ ,\ j}\sqrt{G}+F^{ij}(\sqrt{G})_{,\ j}-\gamma^{a}_{\ ja}F^{ij}\sqrt{G}\} = \\ &=F^{ij}_{\ ,\ i}+2F^{ij}\gamma^{a}_{\ ja}-F^{ij}\gamma^{a}_{\ ja} = \nabla_{j}F^{ij}. \end{split}$$

(where we have taken into account that  $G = g^2$  and  $(\sqrt{-g})_{,i} = \gamma^a_{ia}$ ). That is, if the space is isotropic, equations (23) are just the usual ones:

$$\nabla_j F^{ij} = \frac{\beta}{4\alpha} J^i.$$

**Conclusion:** In comparison to the case of isotropic spaces, there appears a new term in the expression of the current, namely,

$$\zeta^{i} = \frac{1}{\sqrt{G}} (\tilde{F}^{ia} \sqrt{G})_{\cdot a}. \tag{24}$$

This means that in an anisotropic space the measured fields would correspond to an effective current consisting of two terms: one is the current provided by the experimental environment, the other is the current corresponding to the anisotropy of space. The presence of the current  $\zeta^i$  in experimental situations could be noticed if  $\left|(\tilde{F}^{ia}\sqrt{G})_{\cdot a}\right| \approx \left|(F^{ij}\sqrt{G})_{;j}\right|$ . Particularly, if the space is isotropic, then  $A_i = A_i(x)$ , and  $\zeta^k = 0$ .

Relation (23) above does not involve the vertical components  $\tilde{J}^a$  of the current. Hence, for the moment we have no reason to suppose they are nonzero. Still, a formal approach using exterior derivative would emphasize them, and they appear as necessary as "compensating" quantities in order to obtain the continuity equation.

If we formally generalize inhomogeneous Maxwell equation as

$$d(*F) = \frac{\beta}{4\alpha} * \mathcal{J},\tag{25}$$

where \* denotes the Hodge star operator on the manifold TM, then we obtain by direct computation

$$\begin{split} \frac{1}{\sqrt{G}}\{(F^{ij}\sqrt{G})_{;j} + (\tilde{F}^{ia}\sqrt{G})_{\cdot a}\} - F^{ij}N^a_{j\cdot a} &= \frac{\beta}{4\alpha}J^i \\ \frac{1}{\sqrt{G}}(\tilde{F}^{ai}\sqrt{G})_{;i} &= \frac{\beta}{4\alpha}\tilde{J}^a, \end{split}$$

where  $\mathcal{J} = J^i \delta_i + \tilde{J}^a \dot{\partial}_a$  is as in (21).

The first set of equations is nothing but (23) obtained by means of variational methods, while the second one is new. We notice the appearance of the vertical components  $\tilde{J}^a = \frac{4\alpha}{\beta} \frac{1}{\sqrt{G}} (\tilde{F}^{ai} \sqrt{G})_{;i}$ .

With the above expression of  $\mathcal{J}$ , there holds the generalized continuity equation:  $d(*\mathcal{J}) = \frac{4\alpha}{\beta}d(d(*F)) = 0$ , which is,

$$div \mathcal{J} = 0.$$

We notice that the divergence  $div(J^i\delta_i)$  of the horizontal current is not equal to zero. In order to have charge conservation  $div \mathcal{J} = 0$ , the new quantity (formally introduced)  $v \mathcal{J} = \tilde{J}^a \dot{\partial}_a$  is needed.

#### Comparison to existent results:

A previous approach for the equations of electromagnetism in anisotropic spaces was made by R. Miron and collaborators, [3], [4], where the definition of the electromagnetic tensor is made by means of deflection tensors of metrical linear connections. There, it is proposed an *internal electromagnetic tensor* (with h-h and v-v components), of a Lagrange space (M, q),

$$F = F_{ij}dx^j \wedge dx^i + f_{ab}\delta y^a \wedge \delta y^b, \tag{26}$$

where  $F_{ij} = \frac{1}{2}(y_{j|i} - y_{i|j})$ ,  $f_{ab} = \frac{1}{2}(y_{a|b} - y_{b|a})$  are defined by means of covariant derivatives attached to a certain (metrical) linear connection  $D\Gamma(N)$ .

In the respective works, only position dependent potentials A(x) are considered, leading to  $F = F_{ij} dx^j \wedge dx^i$  (and  $f_{ab} = 0$ ).

Here, we propose an alternative definition of the electromagnetic tensor (12),(13) (with horizontal hh- and mixed hv- components instead of hh- and vv- ones as in (26)), based on the idea that in anisotropic spaces, the electromagnetic potential is generally direction dependent, which corresponds to the physically testable situation. Maxwell equations are obtained here as solutions of a variational problem and in terms of exterior derivatives, and they differ from the ones obtained for (26). Moreover, the new components  $\tilde{F}_{ia}$  of our electromagnetic tensor have precise physical meanings, since they are tightly related to Lorentz force. Also, newly appearing currents have a precise role in making continuity equation fulfilled.

An analogue of (26) is obtained if we consider the Lorentz nonlinear connection, [5], [3], of coefficients  $\bar{N}^i{}_j = N^i{}_j - \frac{q}{c} F^i{}_j$  and the linear connection given by  $\bar{D}\Gamma(N) = (\bar{L}^i{}_{jk}, \bar{C}^i{}_{jk} = -g^{il}A_{l\cdot jk})$ , where  $\bar{L}^i{}_{jk} = \frac{1}{2}g^{ih}(g_{hj;k} + g_{hk;j} - g_{jk;h})$ . Then, F can be described by

$$F_{ij} = \frac{1}{2}(y_{j||i} - y_{i||j}), \quad \tilde{F}_{ia} = g_{ia} - y_{i}||_{a}$$

(where  $||_i$ ,  $||_a$  denote the associated covariant derivations).

#### Conclusions:

In the present paper we show that anisotropic electromagnetic potentials lead to additional terms in the equations of motion of charged particles. Starting from these, we build a generalization of the electromagnetic tensor, which leads to extra homogeneous Maxwell equations and additional terms in the expression of currents.

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